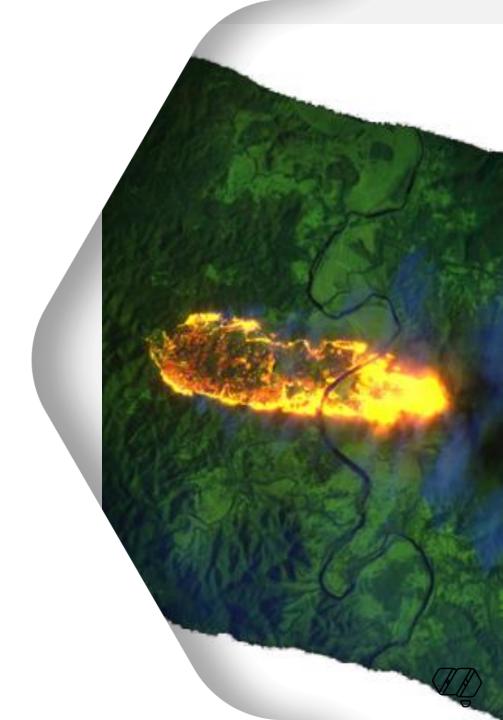


# T4-A2: Capturing uncertainty in bushfire spread prediction

#### **Michael Storey**

Associate Researcher University of Wollongong



## Capturing uncertainty in bushfire spread prediction

#### Goals

- A Bayesian probabilistic bushfire rate of spread model for operational use.
- Tools and approaches to generate and communicate probabilistic predictions.
- A rate of spread database and processing package

#### **Completion**

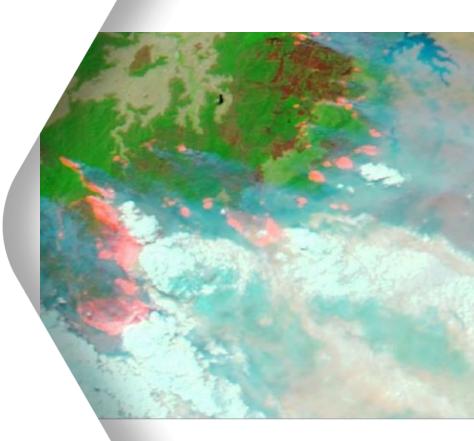
Early 2027

#### **Team**

 University of Wollongong: Michael Storey, Michael Bedward and Owen Price

#### **Contact**

mstorey@uow.edu.au

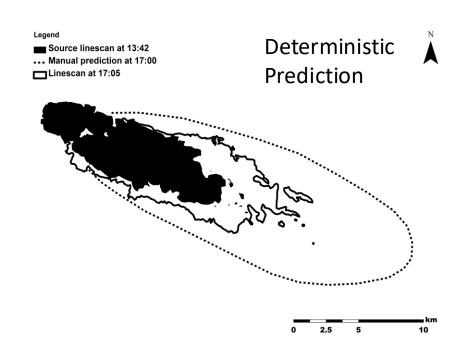




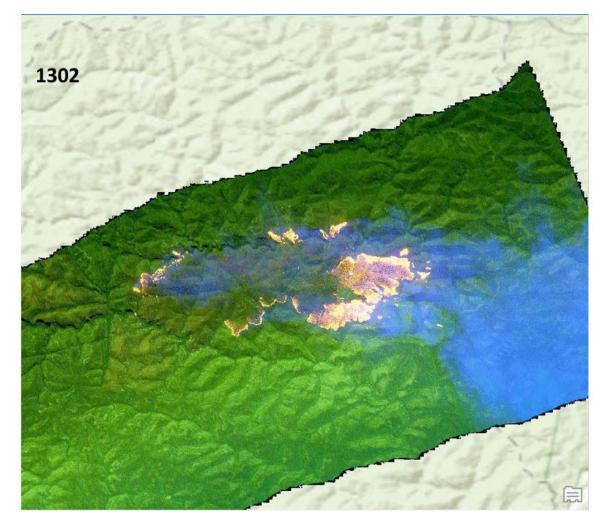
## Why a Bayesian model for rate of spread?

# We usually predict spread based on a few variables. But bushfire spread complex:

- Topography variation
- Wind gusts
- Extreme fire behaviours
- Spotting interactions
- Atmospheric interaction



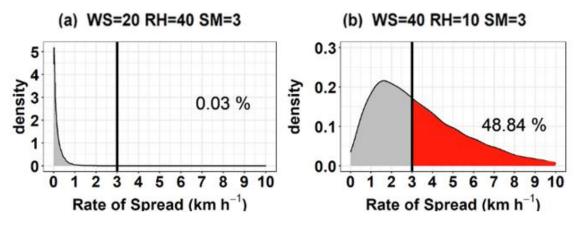
We need a way to represent this uncertainty in ROS predictions





#### Bayesian prediction example

#### Bayesian prediction examples



Based on all the examples of fire spread we have from line scans, and given these conditions, there is a  $\sim$ 49 % chance that fire ROS will be faster 3 kmh.

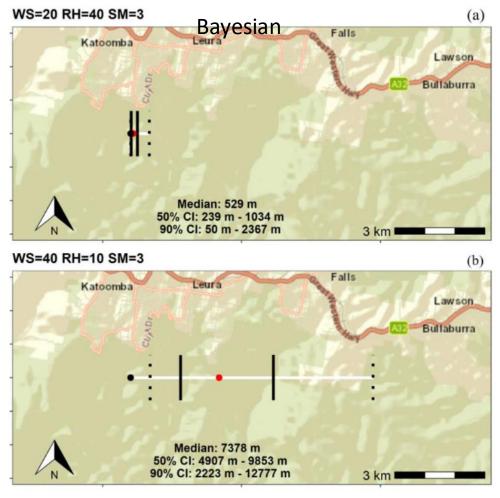


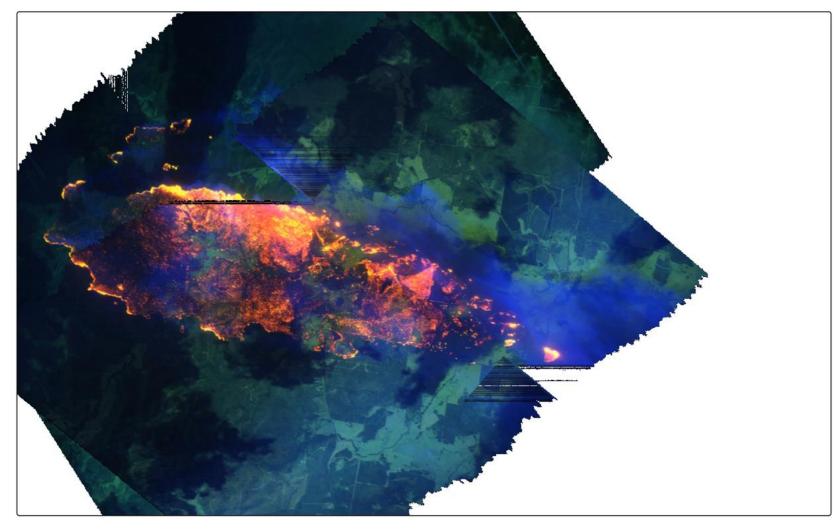
Fig. 8. Map representation of predicted spread distance over 1 h derived from the Bayesian model predictive distributions for different weather conditions (a = mild, b = more extreme), as in Fig. 7. Black dot is start point, red dot is median predicted distance, black lines show the 50% credible interval (CI), black dotted lines show the 90% CL. Fire path (represented by white line) is simply based on a spread bearing of 90°. Location for this example is in the Blue Mountains area, NSW, Australia. WS, wind speed (km h<sup>-1</sup>); RH, relative humidity (%); SM, soil moisture (kg m<sup>-2</sup>).

After one hour, the fire will most likely end up somewhere between the black lines. If the fire has extreme behaviour, there is a small chance it could spread as far as the black dotted line.

## Fire progression data

- → Work to date
  - Collating data from agencies and previous work (Thanks RFS, CFA, DEECA, DFES)
  - Collating data from previous work at UOW
  - Mapping fire progressions
  - Building prototype processing package
  - Building prototype database

scan at 2:37 PM

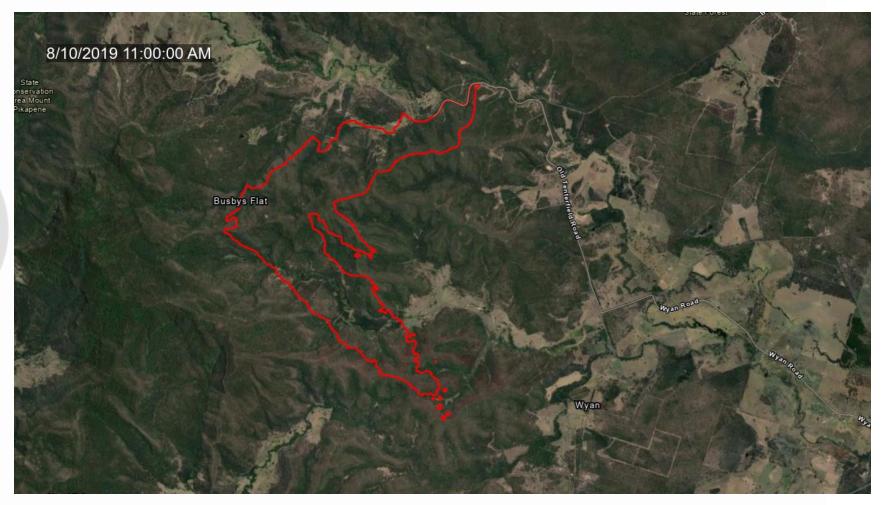


Approach to mapping progressions and measuring ROS

## Fire progression data

#### → Work to date

- Collating data from agencies and previous work (Thanks CFA, DEECA, RFS, DFES)
- Collating data from previous work at UOW.
- Mapping fire progressions
- Building prototype processing package
- Building prototype database



20 min – 5 hour timesteps.



#### Processing package

- → Prototype package
  - Search data online and search prototype database
  - Download to one place
  - Speed up mapping + ROS measurement
  - Manage database



Landsat & Sentinel 2 images

(Online: GA STAC)



Daily VIIRS\MODIS hotspots & images

(Online: NASA GIBS)



Aircraft line scans

(UOW Database.
Originals from RFS,

DEECA, DFES)



Progression polygons (UOW Database)



BARRA weather (Online: BOM NCI)



Himawari 8/9 images

(Online: BOM NCI)



Automated rate of spread measurement



Database functions



Meta/Facebook AI model based mapping



#### Prototype bushfire progression database



-9000 line scans (DEECA/RFS/DFES)

-Satellite images



3300 progressions

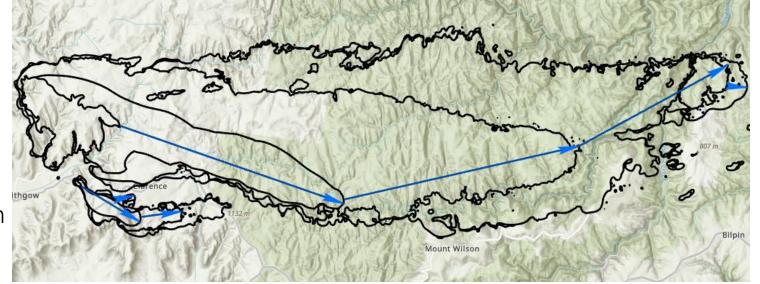


Progressions linked to images



#### → Advantages

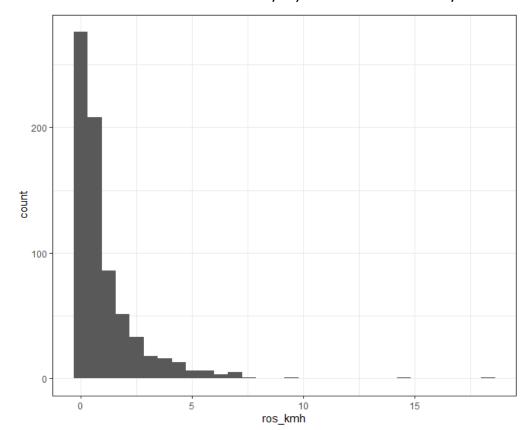
- Consistent polygon attributes.
- Easily searchable by time & location.
- Links to other data/other data can be added.
- Substantially speed up data collection phase of research.
- Continually assess ROS model performance (+ update models)

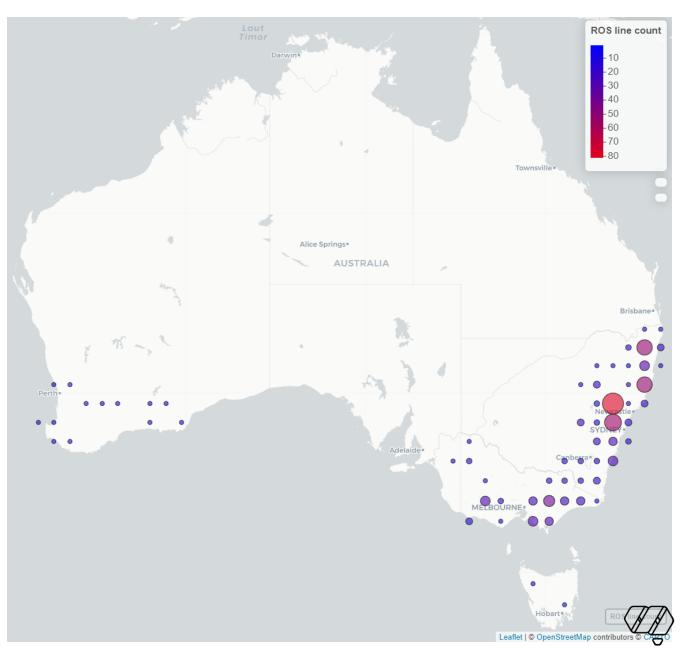




# Prototype bushfire progression database

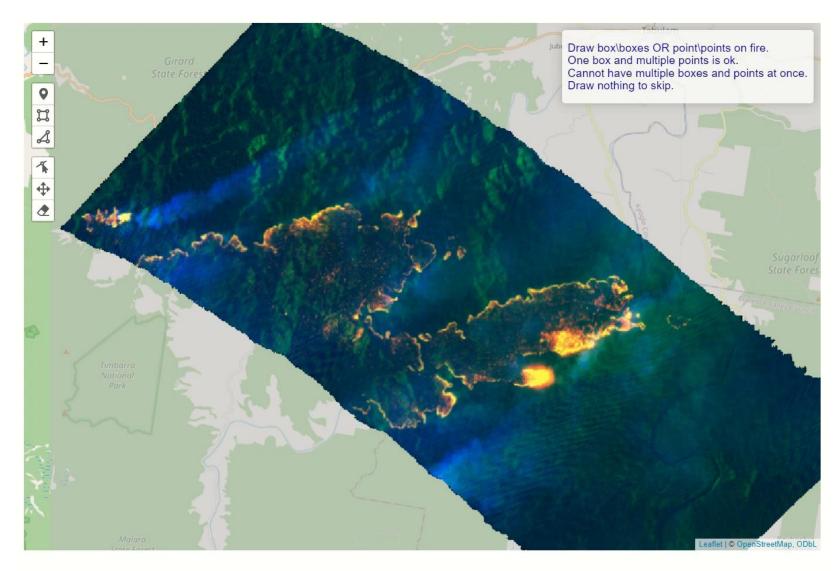
- → Some ROS stats
  - 727 ROS lines (so far)
  - 33% > 1 km/h
  - 9% > 3km/h
  - Mean 1.1 km/h, max. 18.3 km/h





### Faster progression mapping

- → Testing a process to create polygons
  - Mostly automated with some manual input and oversight.
  - Meta "Segment Anything" model
  - Time is saved by:
  - -automatically loading scans
  - -auto creation of initial fire polygon via Meta model.
  - -auto adding of attributes (e.g. scan time)
  - -auto save to file (shp or gpkg)
  - Works best where edge is clear







## Database and processing package future?

- → Feedback on this idea is welcome
  - What aspects are useful in fire agencies?
  - What is already being used in fire agencies?
  - What's missing?
  - Any feedback/ideas for development?
  - mstorey@uow.edu.au



A national database of wildfire progression and wildfire scans. Publicly available (?) and updated yearly.



Further development of R package functions including developing a web app.



Deploy R package and app and agree on process to update database.



Add other selected data for fire reconstructions/ research (ICON/Emap records, PM2.5, fuel moisture records, weather, water drops, FLIR images etc).

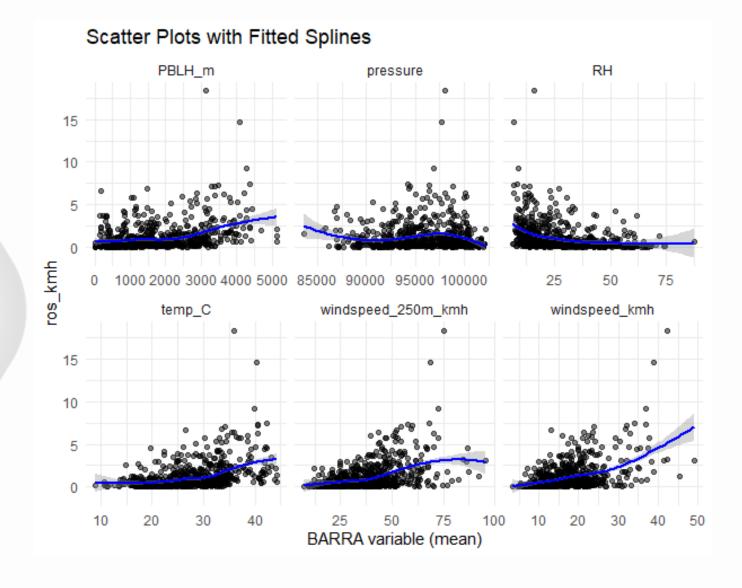


Add tables linking fire spread and line scans to extreme fire behaviours, e.g. VLS, pyroCB.



### Next steps

- → Project completion early 2027
  - Add more progressions?
  - Sampling fuel and weather
  - Fitting and testing models
  - Working with RFS and other agencies to develop prototype operational tool
  - Develop database + processing package???





Contact:
Michael Storey
University of Wollongong
mstorey@uow.edu.au

